

ATTORNEY DOCKET NO.: 066477-0012  
Application No.: 09/857,348  
Page 2

**IN THE CLAIMS:**

Please cancel claim 4 without prejudice or disclaimer.

Please amend claims 1-3, 5-7 and 12-14 as follows:

1. (Currently Amended) An industrial robot ~~Robot~~ including at least one linkage device in which pull rods are arranged in a multi-joint system where the joints include three-axle ball and socket joints, wherein a bearing means element is fixed so that the bearing means element does not rotate in a housing in the socket of a joint, the bearing element further includes friction-increasing means in the form of grooves, the housing including a surface against which the bearing means element abuts and the surface being provided with friction-increasing means in the form of complementary grooves engageable with the grooves provided on the bearing element to increase friction between the surface and the bearing means element.

2. (Currently Amended) The robot according to claim 1, wherein the bearing means element comprises an annular bearing means element.

3. (Currently Amended) The robot according to claim 1, wherein the friction-increasing means is structured as to penetrate the bearing means element effecting a permanent deformation.

4. (Cancelled)

5. (Currently Amended) The robot according to claim 1, wherein the bearing means element abuts with the surface and is pressed thereagainst to fit tightly.

ATTORNEY DOCKET NO.: 066477-0012  
Application No.: 09/857,348  
Page 3

6. (Currently Amended) The robot according to claim 4 1, wherein the grooves provided on the bearing element and the surface are oriented primarily parallel with the central axis of the bearing means element.

7. (Currently Amended) The robot according to claim 1, wherein the bearing means element is comprised of a polymer material.

8. (Previously Amended) The robot according to claim 1, wherein the robot comprises a delta robot.

9. (Cancelled)

10. (Cancelled)

11. (Cancelled)

c)  
(u-a)  
14. 12. (Currently Amended) A method for eliminating risk of play in a three-axle ball and socket joint in an industrial robot, comprising the steps of providing at least one linkage device for the robot, the device having pull rods arranged in a multi-joint system where the joints each comprise the three-axle ball and socket joint, providing a socket of the joint with a housing to accommodate a bearing means element, providing the bearing element with friction-increasing means in the form of grooves, providing the housing with a surface against which the bearing means element abuts, fixing the bearing means element such that the bearing means element does not rotate in the housing, the fixing step being effected by providing the surface with friction-increasing means in the form of complementary grooves engageable with the grooves

ATTORNEY DOCKET NO.: 066477-0012  
Application No.: 09/857,348  
Page 4

provided on the bearing element, and engaging the friction-increasing means with the bearing means element when the bearing means element is positioned in place.

13. (Currently Amended) The method according to claim 12, comprising the further step of pressing the bearing means element to fit tightly in place in the housing of the joint socket.

<sup>c1</sup>  
(amended) 14. (Currently Amended) The method according to claim 12, comprising the further step of deforming the material of the bearing means element by permanent deformation by the friction-increasing means when the bearing means element is placed in position.